# **MODEL QUESTION**

# MANMOHAN TECHNICAL UNIVERSITY

# OFFICE OF THE CONTROLLER OF EXAMINATIONS 2080. Asar

2080, Asar				
Fa Pr	vel: Bachelor culty: School of Engineering ogram: CIVIL oject: ENGINEERING MECHANICS		Year/P F.M.: 50 P.M.: 20 Time: 3	0
Group A (Attempt ALL Questions:)			$[10 \times 1 = 10]$	
	<ul> <li>Choose one answer out of four</li> <li>Use black ball pen for shading of Sheet which you have provided</li> <li>No mark will be awarded for combined which of the following s is a branch a. Statics and Kinetics b. Statics &amp; Kinematics</li> </ul>	only one circle for corred. d. utting, erasing, over wri	ting and multiple circles sh	ading
2)	The center of mass of a system of pb. Position of Particle c. Masses of particle	b. Re	d upon lative distance between pa ce acting on particle	articles
3)	If P>Q and P and Q are acting along a same straight line, but I opposite direction, the resultant is a. P+Q b. P/Q c. P-Q d. Q/P			
	If no force is applied to a moving o  a. Tension b. Momentum	c. Impulse	d. Friction	٩
٦)	DKI (Degree of Kinetic Indeterminacy) of given figure is (Fig:1) a. 2 b. 6 c. 8 d. 9			
6)	If m>2j-r, Where m= no. of members a. Perfect b. Deficient	er, j= no. of joint, r= no. c. Redundant		Fig:-1
7)	The center of Gravity of Semicircul distance of from base of diam a. $r/(2\pi)$ b. $4r/(3\pi)$			ndius at a
8)	If we use link support in a structura a. 1 b. 2	al system, the how man c. 0 d. 4	y unknowns will we have?	
9)	what will the equilibrium will be achieved			
	<ul> <li>a. The three axis of body weight direction</li> </ul>	b. The ground	c. The rope direction	d. The
10) The moment at A is (Fig:-2)				3 Kn/m

d. 6 kN-m

b. 9 kN-m c. 10 kN-m

b. 12 kN-m

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#### **Group B (Attempt any eight questions)**

[8\*2=16]

- 1. State and Prove Varignon's Theorem.
- 2. Explain High-tensioned friction grip bolts and its free body Diagram.
- 3. Define rigid body. Explain the transmissibility of force and its limitation.
- 4. State and prove parallel axis theorem for moment of inertia.
- 5. What are the equation of Static Equilibrium for 2-D and 3-d analysis of Particle and Rigid Body?
- 6. Differentiate between Mechanism and Structure with Sketch.
- 7. Explain about truss and its types.
- 8. Explain free body diagram and its importance.
- 9. Determine Degree of Kinematic Indeterminacy (DKI) of Given Figure-3

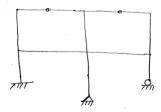


Figure-3

#### **Group C** (Attempt all questions)

10. Determine the resultant force and Moment about point O (Figure-4) [4]

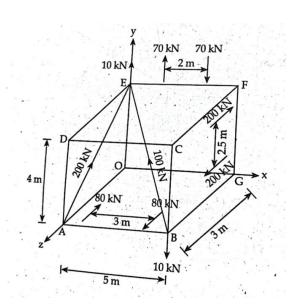


Figure-4

11. Determine the centroid of the hatched area by Direct Integration Method. (Figure-5)

[4]

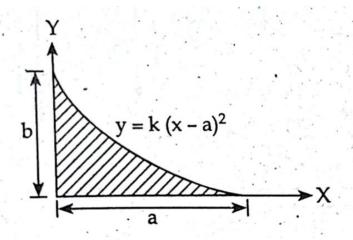


Figure-5

12. a. Draw the axial force, shear force and bending moment diagram of the given frame. (Figure-6) [8]

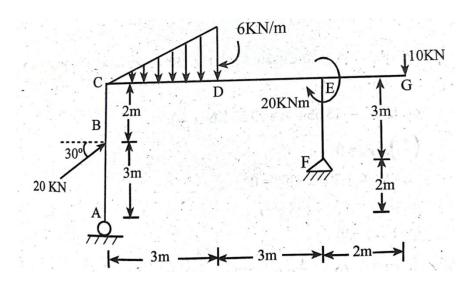


Figure-6

[4]

[4]

### 13. Determine force developed in member force of given truss (Figure-7)

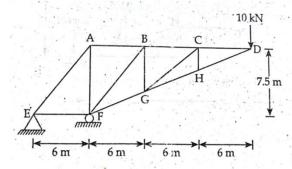


Figure-7

## 14. Determine the Magnitude, direction and position of resultant force . (Figure-8)

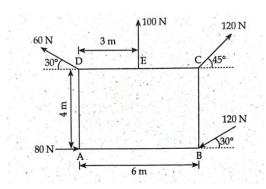
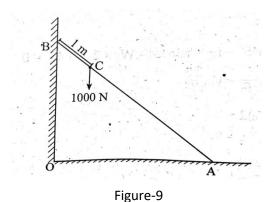


Figure-8 **Or** 

A ladder shown in figure-9 is 4 m long and is supported by a horizontal floor and a vertical wall, the coefficient of friction at wall is 0.3 and floor is 0.45. The weight of ladder is 300N . The ladder supports a vertical load 1000N at c. Determine the reaction at A and B and Compute the least values of  $\theta$  at which ladder may be placed without slipping to right. [4]



\*\*\*\*\* All the Best \*\*\*